SSt-1500-V

DSP-Based Digital Servo Drive

The SSt-1500-V is the latest in Teknic's line of DSP-based servo drives. This unit improves on its predecessor's ability as a high-bandwidth, fully digital, DSP-based amplifier that accepts ±10V analog torque or velocity commands. Upgrading a conventional "dumb" amplifier to an SSt-1500-V will improve tracking, smoothness and settling time.

In velocity mode, the drive utilizes a proprietary servo algorithm that delivers microsecond level response to velocity errors to permit precise motor control. Moreover, this algorithm helps the drive to distinguish between motor feedback quantization errors and real velocity errors to eliminate self-generating velocity error.

In addition to a unique servo algorithm, the drive removes a little-known flaw present in other amplifiers to further optimize motor performance. All other amplifiers servo control current, not torque. So, servo systems that use other amplifiers actually run *open-loop* with respect to torque!

Servo controlling torque requires synchronized control of all motor phases with respect to the magnetic field of the motor's rotor. Conventional amps control each motor phase with a separate, dissociated current loop servo. This scheme ignores the fact that the motor phases are tied together and thus interdependent. Furthermore, small errors in each phase can combine to create a large vector (torque) error. These torque errors lead to inadvertent velocity errors.

The SSt-1500-V employs a proprietary torque control method: *sinewave, vector feed-forward with DQ decoupling*. This method constantly measures all the variables required to accurately calculate the true torque output (and the out-of-phase currents which only heat the motor) and continuously works to servo the torque to the commanded value and the out-of-phase currents to zero. So in the SSt, the torque is truly under closed-loop control. This actively removes errors in motor torque and preempts the resulting velocity error.

So, with the same servo controller, OEMs will see smoother motion and tighter velocity control by simply replacing their velocity amplifiers with SSt-1500-V drives.

CUTTING EDGE VELOCITY CONTROL

Blending proprietary velocity control with advanced closed-loop torque control yields excellent performance potential.

Uncompromised Velocity Control

Combining enhanced PIV-derived velocity gain control with an advanced velocity feedforward significantly improves velocity control performance without the audible noise and high frequency chatter of traditional servo solutions.

Smooth Motion

The SSt-1500-V provides exceptional smoothness in all phases of motion. By eliminating torque error, there is no need for the controller or amp to dither the command to adjust for torque output mistakes. This mitigates velocity ripple while simultaneously improving velocity tracking performance and robustness.

Anti-Resonance Torque Loop

The digital torque loop is accessible for excellent resonance control. This provides optimal performance with axes that suffer from in-band resonances.

Burn-Out Protection

The amp's DSP features a real time algorithm that tracks actual torque demands on the motor and compares that to the motor's continuous capability to eliminate motor burn-out.

FLEXIBLE, LOW EFFORT INTEGRATION

The SSt has OEM friendly features designed to make upgrading performance quick & painless.

Drop-in Controller Compatibility

V-series SSt drives accept a ±10V analog torque or velocity command and are compatible with most servo controllers. Thus they require little or no software changes to integrate.

Universal Motor Interface

SSt drives control rotary and linear servomotors, brush motors, galvos, voice coils, etc. from virtually any manufacturer without electrical restriction on the motor.

Development/Assembly Feature Examples

- Robust PIV compensator eliminates production tuning.
- The V-series provides intuitive diagnostics to qualify production machines and troubleshoot systems rapidly.
- QuietDesign™ EMI reduction system eliminates shield clamps, ferrite slugs, etc. required to meet CE.
- OEM cabling is robust (automotive-style, four-point, gas-tight contacts) and can be built by automated equipment. Teknic offers CAD drawings at no charge, so cables are quickly adaptable and economical to build.
- Daisy chain power avoids star pattern complexity.

ADDITIONAL CAPABILITIES...

Software Scope

Now engineers and technicians can view, configure and troubleshoot the entire motion system using nothing but QuickSet software. A built-in oscilloscope enables quick troubleshooting by providing detailed information about servo drive performance. Advanced triggering modes allow you to capture data related to the start or finish of a move or even a safety shutdown event. View any monitor port variable (commanded torque, actual torque, etc.) alongside specific move status (idle, move active, etc.) or drive status (shutdowns, limits, saturation, etc.). This easy-to-use tool provides an effective method for system evaluation, configuration and diagnosis.

Shutdown History

Quickly discover the root cause of machine problems: A historical view of recent fault activity is captured which allows engineers and technicians to retrace a series of safety shutdowns in a machine.

Extremely Fast Torque Response Time

Sinewave commutation with vector feed-forward and DQ decoupling provides near-zero torque response time *at any speed.*

Elimination of Motor Burn-out

Motor burn-out is eliminated using true RMS limiting and no added wiring or sensors. It is much faster and more effective than I^2t or thermostats.

SmartSaturation™

This dynamic algorithm maintains elegant motor control in the event of voltage and/or current saturation.

Multiple Power Inputs

Dual input power connectors allow for daisy chain simplicity.

Auto-Calibrating Sensors

The current sensors are continuously monitored and re-calibrated to ensure precise and repeatable performance as power usage and temperatures fluctuate.

Exceptional Noise immunity

The drive fully isolates logic and power, making it highly noise immune. This allows OEMs to avoid the hassle and cost of single point grounding, star power wiring, inductive control, etc. typically required in ±10V systems.

SPECIFICATIONS

GENERAL	Dimensions, in (mm):	7.31 (185) x 4.876 (124) x 1.156 (29).
	Weight, oz (g):	17 (494).
ENVIRONMENTAL	Temperature:	0-40 Degrees C.
	Humidity:	0-95%, non-condensing.
COMPLIANCE	Electrical safety:	EN 61010, UL508C.
	EMI:	EN 50081-2, EN 50082-2.
	Machine safety:	EN 954-1, with proper power control.
OUTPUT POWER	Current:	23 Amps Peak (3 seconds). 9 Amps RMS vertical on metal surface. 11.5 Amps RMS with forced air cooling.
	PWM ripple frequency:	28kHz, center balance vector type.
COMPENSATOR	Position/Velocity control:	Enhanced PIV with feedforwards and settable torque bias.
	Torque control:	Synchronous vector with DQ decoupling and auto calibrating sensors.
ENCODER	Interface:	Single-ended or differential, user selectable.
	Max count rate:	15MHz.
	Features:	Bad sequence detection, digital filtering.
MOTOR COMPATIBILITY	Requirements:	3-phase motor with encoder in any electrical configuration, such as linear, rotary, galvo, voice coil, etc. or DC brush motors.
± 10V ANALOG INPUT	Format:	Differential input, ±10V range.
	Impedance:	>10kΩ.
	Range:	10% of peak per volt.
LIMIT INPUTS	Interface:	TTL with 2kΩ pull-up, digitally filtered.
HALL SENSOR INPUTS	Specifications:	5kΩ pull-up to +5V.
	Features:	Digitally filtered; used for setting torque vector upon initialization; drive can run in hall-less mode.
DEDICATED INTERFACE INPUTS/OUTPUTS	Outputs:	Drive ready; encoder and limits pass-through, +5V.
	Inputs:	Enable power stage; analog torque, analog velocity; encoder; limits.
REAL-TIME MONITOR PORT	Format:	0.5V-4.5V analog signal (0=2.5V).
	Features:	Configurable filtering, sync pulse at move start, wide scaling with high zoom, non-volatile configuration.
	Output variables:	Commanded torque, actual torque, actual velocity, max phase voltage.
PROTECTION & SAFETY FUNCTIONS	Drive protection:	Short circuit (phase-to-phase, phase-to-ground), over temp, over voltage, over current, protected for open windings, fused.
	Motor protection:	True RMS torque limiting, automatic speed limit, motor jam detection, over temp.
	Mechanical safeguards:	Limit switch servoing, adjustable torque and speed limit, encoder bad sequence detection, encoder run-away protection.
INPUT SUPPLY	Input voltage:	20-90 VDC.
	Input current:	Up to 5A RMS, 15A peak (app dependant).
COUNTRY OF ORIGIN	Manufactured in:	USA.